## Knots, Braids and First Order Logic

### Siddhartha Gadgil and T. V. H. Prathamesh

Indian Institute of Science, Bangalore

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## Knot

### Definition

A knot K is defined as the image of a smooth, injective map  $h: S^1 \to S^3$  so that  $h'(\theta) \neq 0$  for all  $\theta \in S^1$ .

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(Image source: Wikipedia)

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# Link

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A link  $L \subset S^3$  is a smooth 1-dimensional submanifold of  $S^3$  such that each component of L is a knot and there are only finitely many components.

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### Definition (Ambient Isotopy)

Two links  $L_1$  and  $L_2$  in  $S^3$  are said to be ambient isotopic if there exists a smooth map  $F: S^3 \times [0,1] \to S^3$  such that

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- Ambient isotopy induces an equivalence relation between links.
- *Knot Equivalence Problem*: Given two knots *K*<sub>1</sub> and *K*<sub>2</sub>, are they ambient isotopic to each other?
- *Unknotting Problem*: Given two knot, is it ambient isotopic to the unknot?

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# Stable Equivalence of Links

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- There is a collection of disjoint, smoothly embedded discs n

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### Definition (Stable equivalence of links)

Two links  $L_1$  and  $L_2$  are said to be stably equivalent, denoted  $L_1 \equiv L_2$ , if there are stabilisations  $L'_1$  and  $L'_2$  of  $L_1$  and  $L_2$ , respectively, that are ambient isotopic.

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#### Theorem

If  $K_1$  and  $K_2$  are knots (regarded as links), then  $K_1 \equiv K_2$  if and only if  $K_1$  is ambient isotopic to  $K_2$ .

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# Link Axioms (First Order Logic with Equality)

Consider a language with signature  $(\cdot, T, \equiv, 1, \sigma, \bar{\sigma})$  such that  $\cdot$  is a 2-function ,T is a 1-function,  $\equiv$  is a 2-predicate, while 1, $\sigma$  and  $\bar{\sigma}$  are constants.

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$$\forall x, y, z \quad (x \cdot (y \cdot z) = ((x \cdot y) \cdot z)$$
 • Shift operation

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# Link Axioms (contd.)

Braid axioms

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Markov moves

- Equivalence relation
  - $1 \forall x \quad x \equiv x$

Image: A = A

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Braid axioms

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- Equivalence relation

$$\forall x, y, z \quad x \equiv y \land y \equiv z \implies x \equiv z$$

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Markov moves

These axioms will be called *link axioms* and any model of these axioms will be called a *link model*.

# Algebraic Formulation of Knot Theory

#### Definition

The n-braid group  $B_n$  is the group generated by  $\sigma_1, \sigma_2, \ldots, \sigma_{n-1}$  with the relations

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#### Definition

An element of  $\cup_{n \in \mathbb{N}} B_n$  is called a braid.

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Every element of the braid group  $B_n$  is associated to a diagram.

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#### Theorem (Alexander)

For every link L, there is an integer m > 1 and a braid  $B \in B_m$  so that L is ambient isotopic to  $\lambda(b, m)$ .

## Definition (Markov Equivalence)

The equivalence relation on  ${\mathcal B}$  generated by the relations

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- $\forall a, b \in B_m, m > 1, (b, m) \cong (aba^{-1}, m).$
- For  $i_k \leq m-1$ ,  $(\prod_{k=1}^m \sigma_{i_k}^{\epsilon_k}, m) \cong (\sigma_1 \prod_{k=1}^m \sigma_{i_k+1}^{\epsilon_k}, m+1)$ .

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#### Theorem (Markov)

For i = 1, 2, let  $m_i > 1$  be integers and  $b_i \in B_{m_i}$ . Then the links  $\lambda(b_1, m_1)$  and  $\lambda(b_2, m_2)$  are isotopic if and only if  $(b_1, m_1) \sim (b_2, m_2)$ .

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#### Lemma

Two links are stably equivalent if and only if given  $\lambda(b_1, m_1) = l_1$ and  $\lambda(b_2, m_2) = l_2$ , then  $(b_1, m_1) \approx (b_2, m_2)$ .

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## Stable Links and Infinite Braids

Siddhartha Gadgil and T. V. H. Prathamesh Knots, Braids and First Order Logic

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## Stable Links and Infinite Braids

### Definition

The braid group  $B_{\infty}$  is the group generated by the set  $\{\sigma_i\}_{i\in\mathbb{N}}$  with the relations

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$$\sigma_i \cdot \sigma_j = \sigma_i \cdot \sigma_j$$
, where  $i, j \in \mathbb{N}, i \ge j + 2$ 

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$$\sigma_i \cdot \sigma_{i+1} \cdot \sigma_i = \sigma_{i+1} \cdot \sigma_i \cdot \sigma_{i+1}$$
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 $\mathcal{T}:B_\infty\to B_\infty$  is a group homomorphism such that

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$$a, b \in B_{\infty}$$
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#### Theorem (Main Theorem 1)

There is a surjective function  $\Lambda : B_{\infty} \to \mathcal{L}$ , where  $\mathcal{L}$  is the set of links upto stable equivalence, such that for braids  $b_1, b_2 \in B_{\infty}$ ,  $\Lambda(b_1) = \Lambda(b_2)$  if and only if  $b_1 \equiv b_2$ .
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• Group Axioms(for closed terms)

$$2 \quad \forall x \quad 1 \cdot x = x$$

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### Theorem (Main Theorem 2)

$$(B_{\infty}, T, \cdot, \equiv, \sigma_1, \sigma_1^{-1})$$
 is a link model.

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### **Canonical Model**

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#### Theorem (Main Theorem 3)

 $(B_{\infty}, T, \cdot, \equiv, \sigma_1, \sigma_1^{-1})$  is a canonical model for link axioms.

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### Implications

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For two closed terms a and b in the carrier set of a link model M and their respective preimages x and y in B<sub>∞</sub> (under the canonical homomorphism), if ¬(a ≡ b) then ¬(x ≡ y). Thus the links corresponding to x and y are different in the sense of stable equivalence and thus upto ambient isotopy.

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- However in the finite models, all the closed terms are markov equivalent to each other.
- This formulation enables us to formulate knot theory in terms of first order logic and thus renders it implementable in Automated Theorem Provers.

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- Braid Groups, Christian Kassel and Vladimir Turaev
- 2 On Knots, Dale Rolfson
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